/\*As you move the front of the distance sensor closer to and away from a solid object or wall, the values should change between 0 to 1023. You can now read values and use them within your code. Check the range for your sensor (not all sensors can read from zero cm); note that some sensors have a minimum distance – although it is always listed in the specifications, try to find it by experimentation. To convert the values to actual distances (in cm or inches), consult the user guide of the sensor.\*/

int ir;

void setup() {

Serial.begin(9600);

}

void loop() {

int ir = analogRead(A0);

Serial.println(ir);

delay(500); // delay in between reads for stability

}